

## **References:**

- [1] Kuo, Benjamin C., Golnarghi, Farid., "Automatic Control Systems", Eighth Edition , John Willy & Sons, New York , 2003.
- [2] Niku, Saeed B., "Introduction To Robotics, Analysis, Systems, Applications", Prentice Hall of India , New Delhi, 2005.
- [3] Groover, Mikell P., "Automation, Production System, and Computer-Integrated Manufacturing", Third Edition, Prentice Hall of India, New Delhi, 2008.
- [4] Klee, Harold., "Simulation of Dynamic Systems with MATLAB and SIMULINK", First Edition, CRC Press, Boca Raton, 2007.
- [5] Dukkipati, Rao V., "Analysis and Design of Control Systems using MATLAB", New Age International Limited, New Delhi, 2006.
- [6] Bayro, Eduardo., Corrochano., Detlef K Ahler., Kinematics of Robot Manipulators in the Motor Algebra., Institute of Computer Science and Applied Mathematics, Christian-Albrechts-University of Kiel.
- [7] Lewis, Frank L., Dawson, Darren M., Abdallah, Chaouki T., Robot Manipulator Control Theory and Practise, Second Edition, Marcel Dekker, New York, 2006.  
 University of Moratuwa, Sri Lanka  
Electronic Theses & Dissertations  
[www.lib.mrt.ac.lk](http://www.lib.mrt.ac.lk)
- [8] Chorlton, F., Text Book of Dynamics, Second Edition, CBS Publishers and Distributors, New Delhi, 2003.