Design and Implementation of an Automatic Wire Cutting and Striping Machine for Small Scale Industry

Sivasangar	Kanagal	lingam
Divabangan	Tallaga	

(148468P)

Thesis submitted in partial fulfillment of the requirements for the degree of Master of Electronic and Automation.

Department of Electronic and Telecommunication Engineering

University of Moratuwa Sri Lanka

July 2019

Declaration

I declare that this is my own work and this thesis does not incorporate without acknowledgement any material previously submitted for a degree or diploma in any other university or institute of higher learning and to the best of my knowledge and belief it does not contain any material previously published or written by another person except where the acknowledgement is made in the text.

Also I hereby grant to University of Moratuwa the non-exclusive right to reproduce and distribute my thesis, in whole or in part in print, electronic or other medium. I retain the right to use this content in whole or part in future works (such as articles or books).

	Date:
K.Sivasangar	
(148468P)	
The above candidate has carried out research for the	ne Master's thesis under my
supervision.	
	Date:
Dr. Chamira U. S. Edussooriya	
Department of Electronic and Telecommunication	Engineering
University of Moratuwa, Sri Lanka.	

Abstract

The trend in the recent industry is to move towards automation. This is driven by a number of

factors such as increasing accuracy and decreasing human errors. This dissertation provides

full overview of the development and design of the automated wire cutting and striping

machine for small scale industrial application. The proposed system is put into practice in real

time

Manual approach is currently used to cut and measure wire that takes more time with

manpower. The effectiveness and accuracy obtained by manual method is really poor. The

specific aim of the automated wire - cutting system is to cut the needed wire length in the

required number of parts. By utilizing the developed system, we can achieve low cost cutting

with reduced cutting process time. This system is less complex in terms of user friendliness

and also portable.

Keywords: Automatic wire cutting, transportable, cost- effective

iii

Acknowledgement

Firstly, I should like to express our sincere gratitude to my supervisor Dr. Chamira Edussooriya,

from the University of Moratuwa, Department of Electronic and Telecommunication

Engineering, for supporting the identification of research issues continually, formulating the

conceptual model, survey data analysis, and reviewing research progress which contributed a

lot to carry out the research successfully.

Also, extend my sincere gratitude to all the non-academic staff from the Department of

Electronics and Telecommunications, the University of Moratuwa and my colleagues for the

many ways in which they have supported me.

Lastly, I thank my loving wife and my friends for their constant support and this milestone

would not be possible without their support.

K.Sivasangar

(148468P)

iv

Table of Contents

Declaration	
Abstract	
Acknowledgement	
Table of Contents	v
List of Figures	vi
List of Tables	
List of Abbreviations	
CHAPTER 1: INTRODUCTION	1
1.1 Ove rview of the Research	1
1.2 Background and Motivation	2
1.3 Research Objectives	3
1.4 Contributions to the Small-Scale Industry	3
1.5 Literature Review	
1.5.1 Structure and Working Principle of PLC	6
1.5.2 Stripping Machine Control System	
1.5.3 Hardware Design and Software Design of Stripping Machine Control Syst	em 7
1.5.4 Existing Technologies in the Automatic Wire Cutting Machine	8
1.5.5 Existing machine available in different scales of industrial market	9
CHAPTER 2: DESIGN AND IMPLEMENTATION OF THE SYSTEM	
2.1 Block Diagram of proposed system	11
2.2 Top View of Proposed System	
2.4 Assembly of Mechanical System	15
2.4.1 Guide Tube	15
2.4.2 Wire cutter	15
2.4.3 Controlling speed of wire cutting and strip machine	16
2.5 Calculation	
2.5.1 Calculation for Torque	18
2.5.2 Stepper motor Transfer function derivation	21
2.5.3 Plotting the Root Locus of a Transfer Function	28
2.5.5 Stepper motor Torque Vs Speed analysis and calculation	33
2.6 Component Analysis for the Proposed System	37
2.6.1 Arduino Uno board	
2.6.2 12 DC wiper Motor	37
2.6.3 Dc Motor Driver	
2.6.4 Stepper motor	38
2.6.5 Stepper motor driver	39
2.6.6 Step down converter	
2.6.7 Servo Motor	
CHAPTER 3: EXPERIMENTAL RESULTS AND DISCUSSION	40
3.1 Output and Results	
3.1.1 Analysis between speed and Accuracy of the System	41
3.2 Cost Analysis	
3.2.1 Cost comparison	
3.2.2 Productivity comparison	44
3.3 Limitations	44
CHAPTER 4: CONCLUSION AND FUTURE WORK	45
4.1 Conclusion	
4.2 Future Scope	45
REFERENCES	46

List of Figures

Figure 1: Constitution of PLC [8]	6
Figure 2: PLC input and output wiring diagram of stripping machine control system [8]	8
Figure 3: ARM LPC2148 controller [9]	
Figure 4: Actual view of wire cutting machine [2]	
Figure 5: Existing wire cutting machine [11]	
Figure 6: Existing small-scale machine [13]	
Figure 7: Block diagram of proposed system	
Figure 8: Flow chart of the system	
Figure 9: Front view of the panel board	
Figure 10: Top view of proposed system [12]	
Figure 11: Wire feeding detail diagram	
Figure 12: Wire feeding detail diagram	
Figure 13: Stepper motor pulley specification [14]	
Figure 14: Speed vs torque characteristics [15]	
Figure 15: Speed vs pull torque [15]	
Figure 16: pull out torque vs motor speed [15]	
Figure 17: With stepper motor, torque increases as the speed of the motor is reduced [15].	
Figure 18: Stepper motor top view	
Figure 19: Stepper motor torque calculation	
Figure 20: Wire cutter	
Figure 21: Flux loop of stepper motor [16]	
Figure 22: Dynamic response of the rotor [16]	
Figure 23: Closed loop feedback system [16]	
Figure 24: Control system	
Figure 25: Step angle vs time	
Figure 26: Closed loop system with PID controller	
Figure 27: Step angle vs time	
Figure 28: Step angle vs time	
Figure 29: Root locus output	
Figure 30: Root locus output	
Figure 31: Root locus output value K	
Figure 32: Step response	
	31
Figure 34: Closed loop encoder feedback system	
Figure 35: Performance curve of nema 17 stepper motor[17]	
Figure 36: Motor power vs speed	
Figure 37: Stepper motor steps vs length calculation	
Figure 38: Wiper motor specification [15]	
Figure 39: stepper motor nema17 [16]	
Figure 40: LM296 circuit diagram [17]	
0	40

List of Tables

Table 1: Specification of existing wire cutting machine	9
Table 2: Specification of existing small-scale wire cutting machine	10
Table 3: Steps vs distance	35
Table 4: Required feet vs error	40
Table 5: Speed vs error	41
Table 6: Required feet vs working hours	43
Table 7: Number of panels vs number of hours	41
Table 8: Cost analysis for wire cutting machine	44
Table 9: Small scale machine vs large scale machine	44

List of Abbreviations

- ARM Advanced RISC Machines
- CPU- Central Processing Unit
- DC Direct Current
- IC Integrated Circuit
- LED Light Emitting Diode
- LCD Liquid Crystal Display
- MEP Mechanical, Electrical and Plumbing
- PIC- Programmable Integrated Circuit
- PLC Programmable Logic Controller
- RPM Revolutions Per Minute